## Chap. 1: Fundamentals of Computer Design

| Topics | Pages | Outcome |
| :--- | :--- | :--- |
| Growth in performance | $2-17$ | Trends in computing industry |
| What are computers made of | $14-24$ | System components |
| Cost model of IC | $17-21$ | Importance of minimizing die size |
| Performance | $24-39$ | What performance means in computing |
| Benchmarking | $26-31$ | The problem of choosing benchmarks |
| Reporting performance | $32-39$ | Averaging methods |
| Quantitative principles | $39-48$ | How to use measurements |
| Amdhal's Law | $40-42$ | How to achieve speed up |
| CPU performance | $43-44$ | CPU performance eqn (notion of CPI) |
| Locality principle | 47 | Justification of many design ideas |
| Parallelism | 48 | Another broad class of design ideas |



- Overall progress is a product of three factors of improvement:
- Technology, Architecture, Compiler.
- $1.17 \times 1.17 \times 1.17=1.6 /$ year .
- No other technological systems (say, airplanes or water-treatment plants) improve that fast.


## Three broad markets

- Desktop computing (business, engineering, amusement) (\$1,000 \$10,000)
- Servers (web, high availability) (\$10,000 - \$10,000,000)
- Embedded computers (appliances, vehicles, hand-held) (\$10 $\$ 100,000$ )

| Feature | Desktop | Server | Embedded |
| :--- | :--- | :--- | :--- |
| Price of system | $\$ 1000-\$ 10,000$ | $\$ 10,000-\$ 10,000,000$ | $\$ 10-\$ 100,000$ (including network <br> routers at the high end) |
| Price of microprocessor <br> module | $\$ 100-\$ 1000$ | $\$ 200-\$ 2000$ <br> (per processor) | $\$ 0.20-\$ 200$ (per processor) |
| Microprocessors sold per year <br> (estimates for 2000) | $150,000,000$ | $4,000,000$ | $300,000,000$ <br> (32-bit and 64-bit processors only) |
| Critical system design issues | Price-performance, <br> graphics performance | Throughput, availability, <br> scalability | Price, power consumption, <br> application-specific performance |

## Important terms related to Computer Architecture

- Implementation: how an abstract description is turned into hardware.
- The instruction set architecture (ISA) is such abstraction.
- HW / SW interface.
- ADD C,A,B.
- Examples of ISAs
- IA-32
- IA-64
- MIPS64
- ARM
- Organization: high level aspects of the design
- memory, bus structure, CPU, I/O
- design of these sometimes called "micro-architecture".
- It is possible to implement the same instruction set architecture using different organizations, resulting in different systems.
- E.x. Different Bus, memory organization, pipeline structure and soon.
- Hardware refers to the specifics of an implementation.
- For example the Pentium II and the Celeron have different hardware.
- It is even possible to emulate a function normally carried out in hardware (say floating point calculations) using software (lists of instructions).


## Task of the Computer Designer

## Functional requirements Required Features

## Application

General-purpose desktop
Scientific/Engineering
Commercial Servers
Embedded

Software compatibility
At programming language
At object code
Operating System
Size of address space
Memory management
Protection

## Standards

Floating point
I/O
Operating System
Network
Programming Language

## Target

Balanced performance for many tasks High performance FP/Graphics
Reliability, availability, scalability
Focus on few features (power, throughput, ...)
re-use existing software
Flexible for designer, new compiler back-end Same ISA

## Necessary OS support

Key
Virtual Memory
Different OS, paging, segmentation
Certain standards may be required by marketplace
Format, arithmetic, IEEE 734, Graphics
ATA, SCSI, PCI
Unix, PalmOS, Windows, CE, IOS
Ethernet, Infiniband
C, C++, Java, FORTRAN: ISA

## Trends

- valid over long time periods, e.g. ISA can last decades
- Clock Rate:
~ 30\% per year
- Transistor Density:
~ 35\%
- Chip Area:
~ 15\%
- Transistors per chip:
~ 55\%
- Total Performance Capability: ~100\%


## Moore's Law

## 2x number of transistors every 12-18 months

"The complexity for minimum component costs has increased at a rate of roughly a factor of two per year. Certainly over the short term this rate can be expected to continue, if not increase. Over the longer term, the rate of increase is a bit more uncertain, although there is no reason to believe it will not remain for nearly constant for at least 10 years. That means by 1975, the number of components per integrated circuit for minimum cost will be 65,000 .
"I believe that such a large circuit can be built on a single wafer."
--- Gordon Moore, 1965


Source: Intel


Source: D. Patterson

## IC Technology

- Feature size (min size of transistor or wire)
- 1971: $10 \mu \mathrm{~m}$
- 2001: $0.18 \mu \mathrm{~m}$
- 2002: $0.13 \mu \mathrm{~m}$
- 2003: $0.10 \mu \mathrm{~m}$
- Quadratic increase in density, linear increase in performance
$\Rightarrow$ Architectural improvement!
- 8, 16, 32, 64 bit architectures (buses, ALU's)
- Pipelines and caches
- Transistor performance benefits from smaller resistance and capacitance.
- Interconnect propagation delay major problem.
- e.g. Pentium 4 accounts for propagation of signals across chip.


## Switching Power

$$
P=f C V^{2}
$$

$\mathrm{f}=$ clock frequency
C = capacitance
$\mathrm{V}=$ voltage

- 2 GHz Pentium consumes $100 \mathrm{~W} \Rightarrow$ Heat removal.
- Alternatively, portable computing requires low power.


## Net Effect: Power Density Increasing Exponentially!



Other "Famous" Predictions
"There is no reason for any individual to have a computer in his home."

Kenneth H. Olson, President of DEC,<br>Convention of the World Future Society, 1977

"640 kilobytes (of computer memory) ought to be enough for anybody."

Bill Gates<br>Founder and head of Microsoft, 1981

## Cost, Price, and Trends

- What is the nature of the cost-performance tradeoff?
- Driven by cost of components
o one important aspect is their change over time.


## Time and volume

- Manufacturing learning curve.
- Yield improves with time.
- Doubling the yield halves the cost.
- Example: DRAM chips have strange business behaviors because of rapid changes, price can be lower than cost for a short moment.
- Microprocessors are less predictable.
- E.g. Pentium III
- Roughly cost x 0.9 for volume doubling.
- Expansion of low-end market has produced "commoditization" with fierce competition and razor-thin margins.



Price of Pentium III at a given frequency decreases over time as yield enhancements decrease the cost of a good die and competition forces price reductions.

## Cost of an IC

## Manufacturing Steps.

- Silicon Crystal Growth extracted from molten silicon bath
- Processed (cleaned to very high level of purity) into cylinder
- Cylinder sliced to make wafers
- Wafers cleaned, polished and chemically processed
- Long sequence of steps involving deposit and removal of substances to etch the circuit according to patterns specified by optical masks.
- Dies cut, tested and packaged.


## MIPS64 R20K WAFER (564 processors)


© 2003 Elsevier Science (USA). All rights reserved.

© 2003 Elsevier Science (USA). All rights reserved.

## Intel Pentium 4

## Cost model

$$
\begin{aligned}
& I C C o s t=\frac{\text { DieCost }+ \text { DieTestCost }+ \text { PackagingAndTestCost }}{\text { FinalYield }} \\
& \text { DieCost }=\frac{\text { WaferCost }}{\text { DiesPerWafer } \times \text { DieYield }} \\
& \text { DiesPerWafer }=\frac{\pi \times \text { WaferRadius }{ }^{2}}{\text { DieArea }}-\frac{\pi \times \text { WaferDiameter }}{\sqrt{2 \times \text { DieArea }}} \\
& \text { DieYield }=\text { WaferYield } \times\left(1+\frac{\text { DefectDensity } \times \text { DieArea }}{\alpha}\right)^{-\alpha}
\end{aligned}
$$

DieYield is from an empirical formula where $\alpha$ reflect the number of process steps (complexity). $\alpha$ can be of the order of 3 or 4. DefectDensity is of the order of $0.4--0.8 / \mathrm{cm}^{2}$.

$$
\text { ICCost }=\frac{\text { DieCost }+ \text { DieTestCost }+ \text { PackagingAndTestCost }}{\text { FinalYield }}
$$

Realistic example: $\$ 8000$ / wafer, 350 raw dies / wafer 60\% good dies, $\$ 80$ to test wafer, \$4/unit to package and final test, 97\% final test yield

$$
\text { DieCost }=\frac{\text { WaferCost }}{\text { DiesPerWafer } \times \text { DieYield }}
$$

DieCost $=$
DieTestCost (good dies) =
ICCost =

## Real World Examples

| Chip $\quad$M <br>  <br>  |  |  | Wafer ost | $\begin{aligned} & \text { efect } \\ & / \mathrm{cm}^{2} \\ & \hline \end{aligned}$ | Area $\mathrm{mm}^{2}$ | wafer |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 386DX | 2 | 0.90 | \$900 | 1.0 | 43 | 360 | 71\% | \$4 |
| 486DX2 | 3 | 0.80 | \$1200 | 1.0 | 81 | 181 | 54\% | \$12 |
| PowerPC 601 | 4 | 0.80 | \$1700 | 1.3 | 121 | 115 | 28\% | \$53 |
| HP PA 7100 | 3 | 0.80 | \$1300 | 1.0 | 196 | 66 | 27\% | \$73 |
| DEC Alpha | 3 | 0.70 | \$1500 | 1.2 | 234 | 53 | 19\% | \$149 |
| SuperSPARC | 3 | 0.70 | \$1700 | 1.6 | 256 | 48 | 13\% | \$272 |
| Pentium | 3 | 0.80 | \$1500 | 1.5 | 296 | 40 | 9\% | \$417 |

- From "Estimating IC Manufacturing Costs," by Linley Gwennap, Microprocessor Report, August 2, 1993, p. 15


## Architect's quandry: price/performance tradeoff:

Given a 20 cm diameter wafer at $\$ 2000, \alpha=4$.
A. Using mid-life process (medium defect density $\mathbf{= 0 . 6}$ )

| Relative <br> Performance | Die Area | Dies/Wafer | Die Yield | Good Die | \$/Good Die |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 0.64 | 478 | 0.69 | 331 | $\$ 6.03$ |
| 2 | 1.23 | 243 | 0.51 | 124 | $\$ 16.19$ |
| 4 | 2.40 | 120 | 0.29 | 35 | $\$ 56.78$ |

B. Using end of life process (low defect density = 0.4)

| Relative <br> Performance | Die Area | Dies/Wafer | Die Yield | Good Die | \$/Good Die |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 0.64 | 478 | 0.78 | 373 | $\$ 5.36$ |
| 2 | 1.23 | 243 | 0.63 | 153 | $\$ 13.08$ |
| 4 | 2.40 | 120 | 0.42 | 51 | $\$ 39.24$ |

Architectural problem: more performance from smaller dies.

- The processor can be $20 \%$ of the cost of a desktop system,
o perhaps $40 \%$ of the total cost is in the motherboard.
- It has a huge impact on the price and performance of the system.
- The next item competing for importance is the monitor! ( $20 \%$ of total cost, $40 \%$ for all I/O: hard disk, DVD).
- The rest is the cabinet and power supply.



## Measuring and Reporting Performance

Problem: if you speak of a car, performance indicators like speed, turning radius, or mileage are measured in physical units. For channels and memory, there are bits and bits/s to measure capacity and bandwidth, but for computers, there is no unit for computation! It is rather hard to define what computation is. As a result, computer performance is always measured relatively to another computer.

There are two aspects:
1.Response time (latency) (needed to get a result from the givens).
2. Throughput (bandwidth) (how much computation per unit of time).

Relative performance:

$$
n=\frac{\text { ExecTime }_{\mathrm{Y}}}{\text { ExecTime }_{\mathrm{X}}}=\frac{1 / \text { Performance }_{\mathrm{Y}}}{1 / \text { Performance }_{\mathrm{X}}}=\frac{\text { Performance }_{\mathrm{X}}}{\text { Performance }_{\mathrm{Y}}}
$$

## Different "Times"

Wall-clock time is the elapsed time to complete a task. This includes I/O, memory, OS overhead, ..., everything. With multiprogramming and multitasking (as in UNIX), for a given task, it changes with the load.

CPU time is the time spent by the CPU on behalf of one task. It is subdivided into user CPU time (time spent by the CPU running user code) and system CPU time (time spent running OS code on the behalf of the user).

The UNIX time command reports all three. For example
prompt\$ time sleep 5
0.00u 0.02s 0:05.02 0.3\%
tells us that the sleep 5 command spent (almost) no CPU time to run, 20 milliseconds to execute OS code and that the elapsed was 5.02 s (per the definition of sleep). It also says that ( $0.0+0.02$ )/5.02=0.3\% of the elapsed time was to do some work.

## What is a task?

We want to be able to predict the performance of a computer: how do we evaluate performance?

1. Real applications: C compiler (if you are code developer), TeX if you are a typesetter, Photoshop if you are a graphic designer, Spice if you are an electronic engineer, MatLab, and so-on.
2. Scripted applications: real applications stripped from I/O.
3. Kernels: A general principle about computing (Knuth) is that programs tend to spend most of their time in a very small portion of the code. (For example, the integrator routine in MathLab, searching and sorting while compiling, manipulating matrices in scientific code).
4. Toy benchmarks: Small and interesting programs, Sieve of Eratosthenes (prime numbers), Towers of Hanoi, Puzzles, Quicksort.
5. Synthetic Benchmarks: Attempt of reproduce the load of a set of programs.

SPEC (Standard Performance Evaluation Committee, www.spec.org) is a consortium dedicated to the design of documented benchmarks suites. There are also PC benchmarks (winbench) or the EEMBC benchmarks (www.eembc.org) which permit code tweaking (why not?).

| Benchmark | Type | Source | Description |
| :--- | :--- | :---: | :--- |
| gzip | Integer | C | Compression using the Lempel-Ziv algorithm |
| vpr | Integer | C | FPGA circuit placement and routing |
| gcc | Integer | C | Consists of the GNU C compiler generating optimized machine code |
| mcf | Integer | C | Combinatorial optimization of public transit scheduling |
| crafty | Integer | C | Chess-playing program |
| parser | Integer | C | Syntactic English language parser |
| eon | Integer | C++ | Graphics visualization using probabilistic ray tracing |
| perlmbk | Integer | C | Perl (an interpreted string-processing language) with four input scripts |
| gap | Integer | C | A group theory application package |
| vortex | Integer | C | An object-oriented database system |
| bzip2 | Integer | C | A block-sorting compression algorithm |
| twolf | Integer | C | Timberwolf: a simulated annealing algorithm for VLSI place and route |
| wupwise | FP | F77 | Lattice gauge theory model of quantum chromodynamics |
| swim | FP | F77 | Solves shallow water equations using finite difference equations |
| mgrid | FP | F77 | Multigrid solver over three-dimensional field |
| apply | FP | F77 | Parabolic and elliptic partial differential equation solver |
| mesa | FP | C | Three-dimensional graphics library |
| galgel | FP | F90 | Computational fluid dynamics |
| art | FP | C | Image recognition of a thermal image using neural networks |
| equake | FP | CP | Simulation of seismic wave propagation |
| facerec | FP | FP | C |
| ammp | Face recognition using wavelets and graph matching |  |  |
| lucas | FP | C90 | Molecular dynamics simulation of a protein in water |
| fma3d | Performs primality testing for Mersenne primes |  |  |
| sixtrack | F90 | Finite element modeling of crash simulation |  |
| apsi | F77 | High-energy physics accelerator design simulation |  |
|  | F77 | A meteorological simulation of pollution distribution |  |

Figure 1.12 The programs in the SPEC CPU2000 benchmark suites. The 11 integer programs (all in C, except one in $C_{++}$) are used for the CINT2000 measurement, while the 14 floating-point programs ( 6 in FORTRAN- 77,5 in C , and 3 in FORTRAN-90) are used for the CFP2000 measurement. See www.spec.org for more on these benchmarks.

## Summarizing Performance

Take $n$ programs and average. Arithmetic mean:

$$
\text { ArithmeticMean }=\frac{1}{n} \sum_{i=1}^{n} \operatorname{Time}_{i}
$$

or weight them:

$$
\sum_{i=1}^{n} \mathrm{Weight}_{i} \times \operatorname{Time}_{i}
$$

A particular choice of weights equalizes running times:

$$
\text { Weight }_{i}=\frac{1}{\operatorname{Time}_{i} \times \sum_{i=1}^{n}\left(\frac{1}{\operatorname{Time}_{i}}\right)}
$$

Normalized times to a reference machine can be averaged geometrically:

$$
\begin{aligned}
& \text { GeometricMean }=\sqrt[n]{\prod_{i=1}^{n} \frac{\text { ExecTime }_{i}}{\text { ExecTime }_{\text {ref }}}} \text {, but since } \\
& \frac{\text { GeometricMean }\left(X_{i}\right)}{\text { GeometricMean }\left(Y_{j}\right)}=\text { GeometricMean }\left(\frac{X_{i}}{Y_{j}}\right)
\end{aligned}
$$

the relative results do not depend on the machine taken as reference.

## Quantitative Principles of Computer Design

Make the common case fast. This is to help deciding where to allocate a given design (or cost) effort to get maximum results. For example, certain computers load and store 64 bit long numbers is faster that bytes because they are optimized for FP operations rather than business applications. There are hundreds of examples.

Amdahl's law (1967) captures this. It was used to make the case for single CPU processors. Suppose we have an enhancement for a given design.

$$
\text { SpeedUp }=\frac{\text { ExecTimeBase }}{\text { ExecTimeEnhanced }}
$$

Define FractionEnhanced, the fraction of computation time concerned by an enhancement. This fraction is sped up by SpeedUpEnhanced.

$$
\text { ExecTimeEnhanced }=\text { ExecTimeBase } \times\left((1-\text { FractionEnhanced })+\frac{\text { FractionEnhanced }}{\text { SpeedUpEnhanced }}\right)
$$

$$
\text { SpeedUp }=\frac{1}{(1-\text { FractionEnhanced })+\frac{\text { FractionEnhanced }}{\text { SpeedUpEnhanced }}}
$$

## Amdahl's Law Applied

Flying New York to Paris (or Brussels to Montréal).
On an airliner, you have 2 hours check-in then 8 hours flight.
What is speedup if you take the Concorde (about 2 times faster flying)?

Computer example:
Consider the enhancement to a processor for Web serving. New CPU 10 x faster than original for Web serving. Original CPU busy with computation $40 \%$ of time and is waiting for I/O $60 \%$ of time. What is overall speedup gained by enhancement?

Only spends $40 \%$ doing work so limited by that amount.

## CPU Performance

Total CPU time for a task (CPU is a clock driven sequential circuit):

$$
\text { CPU_Time }=\text { ClockCycles } \times \text { ClockCycleTime }=\text { ClockCycles } \times \frac{1}{\text { ClockRate }}
$$

Programs (tasks) are made of lists of instructions:

$$
\begin{aligned}
& \text { ClockCyclesPerInstruction }=\mathrm{CPI}=\frac{\text { ClockCycles }}{\text { InstructionCount }} \\
& \text { CPU_Time }=\text { InstructionCoun } \times \mathrm{CPI} \times \text { ClockCycleTim؛ } \\
& \text { CPU_Time }=\frac{\text { Instructions }}{\text { Program }} \times \frac{\text { ClockCycles }}{\text { Instructions }} \times \frac{\text { Seconds }}{\text { ClockCycle }}
\end{aligned}
$$

Significance:

1. First factor is a function of the ISA and of the compiler technology.
2. Second factor is a function of the organization and of the compiler.
3. Third factor is a function of the organization and of the technology.

Faced with a giant tradeoff! The art of computer design is contained in this formula.

How to improve a factor without affecting the others?
It is useful to breakdown this into more components, i.e. by classes of instructions.

$$
\begin{array}{r}
\text { ClockCycles }=\sum_{i=1}^{n} \mathrm{IC}_{i} \times \mathrm{CPI}_{i} \\
\mathrm{CPI}=\sum_{i=1}^{n} \frac{\mathrm{IC}_{i}}{\text { InstructionCount }} \times \mathrm{CPI}_{i}
\end{array}
$$

(Error in Book!).
$\mathrm{IC}_{i}=$ number of instructions of classi executed in a program
$\mathrm{CPI}_{i}=$ average number of clock cycles/ instruction of class $i$
which breaks down the problem into the design of classes of instructions.
(e.g. Total $C C=$ Number of FP operations occuring in program $x$ number of clocks for a FP operation + number integer operations $x$ clocks for integer operations ...)

This also define the notion of instruction mix, which is the relative frequency of occurrence of classes of instructions (e.g. branches, FP, ...), say in a given benchmark.
Ex. gcc

| Op | Freq | CPII | Term |
| :--- | :--- | :--- | :--- |
| ALU | $50 \%$ | 1 | 0.5 |
| Load | $20 \%$ | 2 | 0.4 |
| Store | $10 \%$ | 2 |  |
| Branch | $20 \%$ | 2 |  |
|  |  |  | CPI |
|  |  | 0.4 |  |
|  |  | 1.5 |  |

Other Example:

How to measure these numbers?
Clock speed is known, CPU time is also easy to measure.
How to measure fraction of instruction count and CPI?
Software or hardware simulations:

- Designers add counters in the hardware to count important events (such as number of instructions, or number of clock cycles), periodically saved. This has limited practicality and accuracy.
- Instrumented execution by inserting extra instructions in the code (e.g. tracing memory addresses). Gives exact profile.
- Interrupt the processor at random intervals to get statistics.

Another fundamental principle was observed by Knuth (1960). Most programs are, by definition, highly structured. They rarely use data and instructions in a completely random fashion. The principle of locality observes that data that are used at close time intervals (temporal locality) are also stored close to each other in memory (spatial locality) (because of arrays, loop, structures, due generally to how humans turn their thoughts into programs). This drives most of the ideas in computer architecture - we can exploit this knowledge.

Parallelism is related to performing many operations simultaneously. It is applicable to single processors or to memory management as well. In fact, modern CPUs can executes 10's of instructions simultaneously and perform many memory transactions simultaneously. It is applicable to basic circuits (such as carry-look-ahead adders) to entire systems (many CPU or hard drives operating simultaneously).

In an ideal CPU, every transistor would switch in concert with 100 million others, doing something useful. Not only we are far from this ideal, but also far from the system of the some 100 billions neurons firing in our heads!

Pitfall: The relative performance of two processors with the same ISA can be judged by clock rate (or by a single benchmark suite).
No! the architecture can differ.
Fallacy: Benchmarks remain valid through time.
No! they must be redesigned periodically to account for evolving application and computing technology.
Pitfall: Hand coded assembly code and compiler generated code can be compared.
No! Each has its use. Hand code can make use of very special instructions to boost performance in some applications. On the other hand, in many computers, compilers do better jobs at taking advantage of pipelines and other features.
Fallacy: Peak performance tracks observed performance.
No! "Peak performance is the performance guaranteed not to be exceeded". There can be huge gaps.
Fallacy: The best computer design is the one that optimizes the primary objective without considering implementation.
No! complex implementations take a long time to develop. Each week of delay is equivalent to $1 \%$ loss of performance.

Pitfall: Neglecting the cost of software.
Don't!
Pitfall: Falling prey to Amdahl's Law.
Measure usage before optimizing.
Fallacy: Synthetic benchmarks predict real performance.
No! For example compilers discard useless code and are capable of all kind of code transformations.
Fallacy: MIPS is an accurate measure of performance.
No! MIPS (= ClockRate $/\left(\mathrm{CPI} \times 10^{6}\right)$ are ISA and program dependent. e.g. clock: 1 cycle / second.

Example:
FP software: 4 instructions (1 clock each) to perform FP operation (1FP/4s)
= 4 instr/4 sec = 1 instr/sec -> high MIPS
FP Hardware: 1 instruction (2 clocks long) to perform FP operations
$=2$ instr/4 sec $=0.5$ instructions / sec -> Lower MIPS
even though does more useful work in 4 seconds (completes 2 FP operations/4s)

